

Sparse Sky Grid for Coherent network analysis

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with

Olivier Rabaste and Éric Chassande Mottin, APC, Paris
(arXiv:0905.4832)

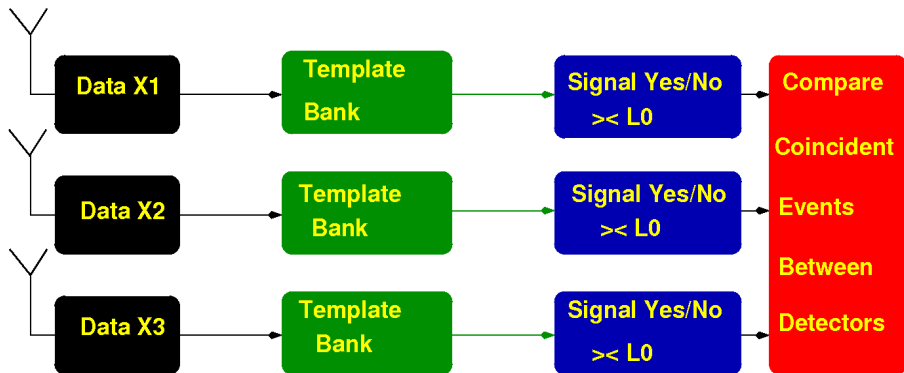
AIGO-2010, 24 February 2010

Network Analysis – Sky Sampling Problem



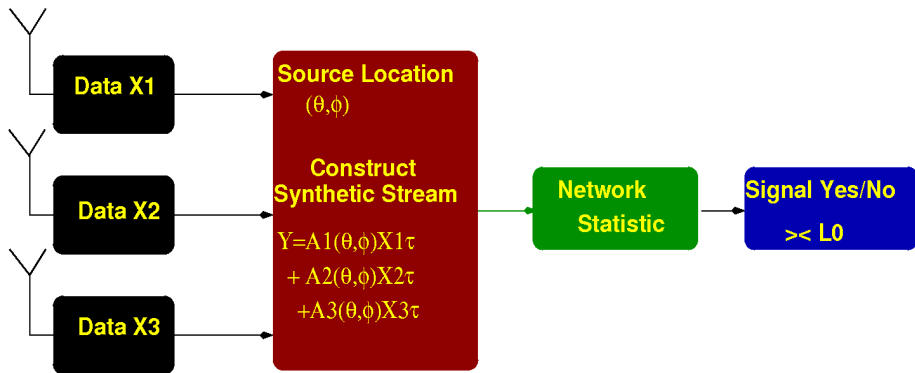
Network Analysis – Sky Sampling Problem

Coincident Network Analysis

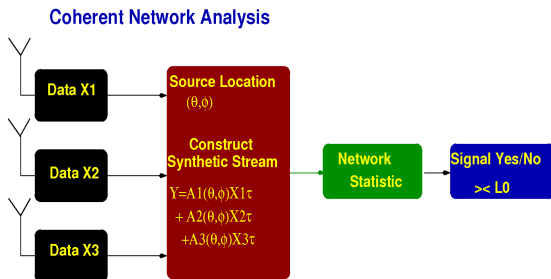


Network Analysis – Sky Sampling Problem

Coherent Network Analysis



Network Analysis – Sky Sampling Problem

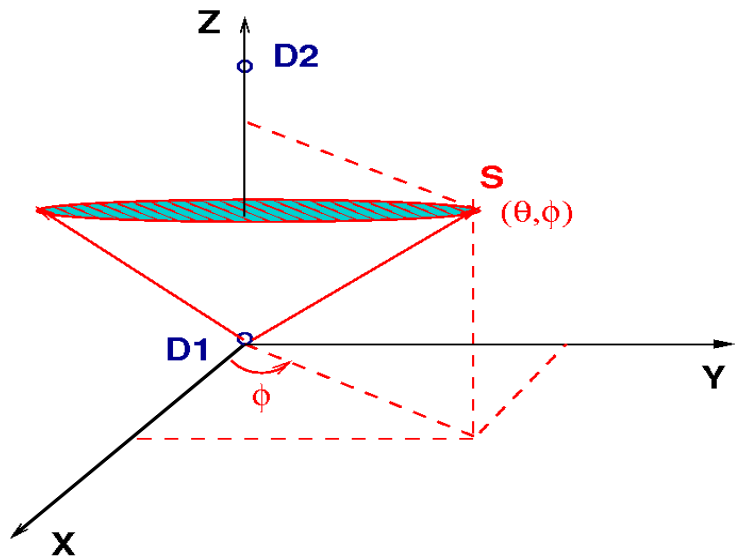


How to sample the sky ?

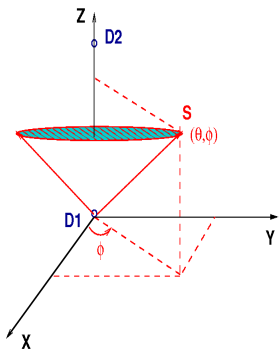
General Practice: Uniform Sky-grid

Intuition: Sky-grid tuned to signal and network geometry

Two Detector Network



Two Detector Network



Light travel time between D1-D2 ;

$$T2 = ||D1 - D2||/c$$

Wave arrival time delay at D2 w.r.t. D1

$$\tau_2 = T2 \cos(\theta)$$

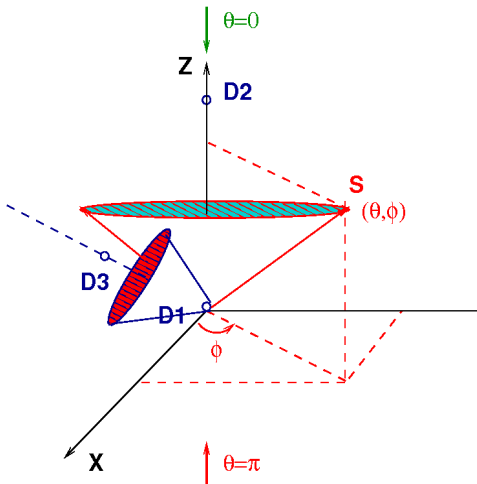
$$-T2 \leq \tau_2 \leq T2$$

Two detectors network;

Determine θ

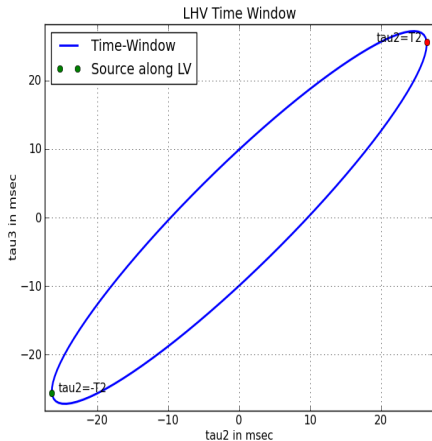
Degeneracy in ϕ .

Three Detector Network: (τ_2, τ_3)

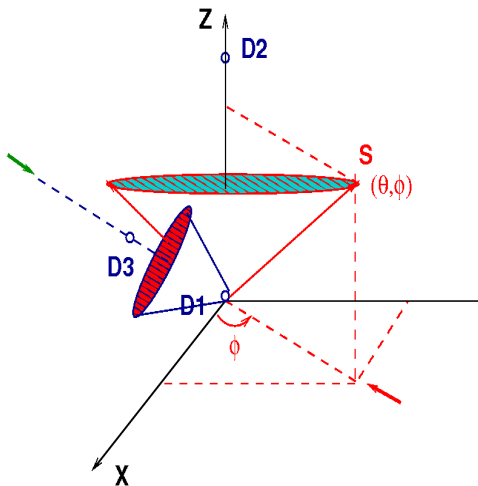


$$\tau^T \mathbf{A}_T \leq \mathbf{B} \quad \tau^T = [\tau_2 \ \tau_3], \quad \mathbf{A}_{2 \times 2}$$

Time window == Ellipse in (τ_2, τ_3)

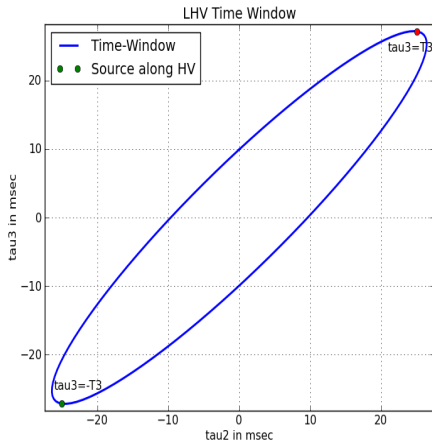


Three Detector Network: (τ_2, τ_3)

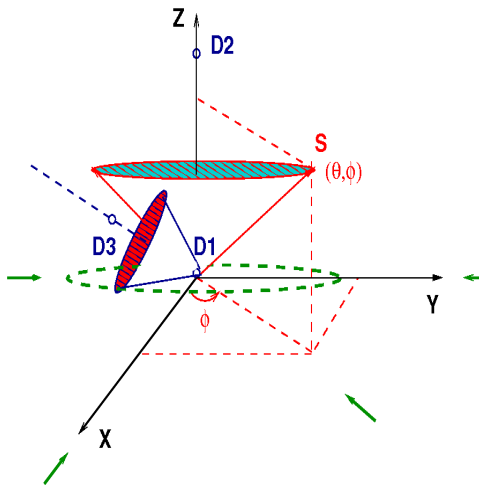


$$\tau^T \mathbf{A} \tau \leq \mathbf{B} \quad \tau^T = [\tau_2 \ \tau_3], \quad \mathbf{A}_{2 \times 2}$$

Time window == Ellipse in (τ_2, τ_3)

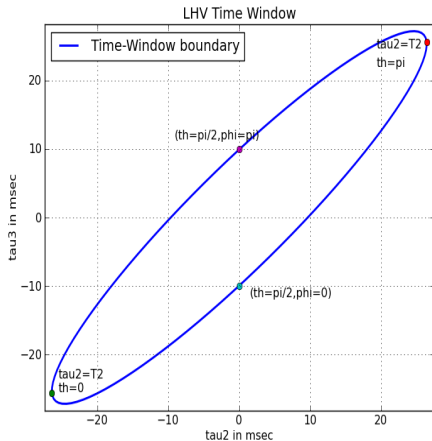


Three Detector Network: (τ_2, τ_3)

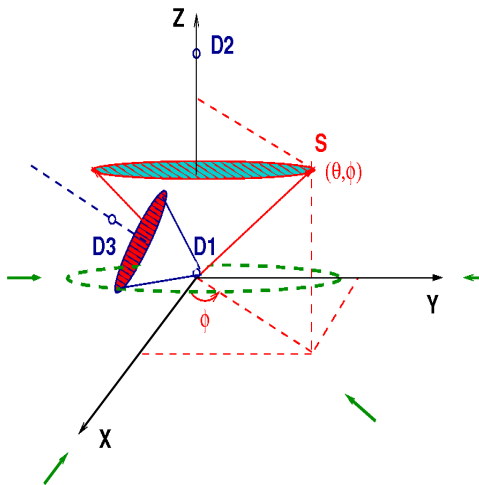


$$\tau^T \mathbf{A}_T \leq \mathbf{B} \quad \tau^T = [\tau_2 \ \tau_3], \quad \mathbf{A}_{2 \times 2}$$

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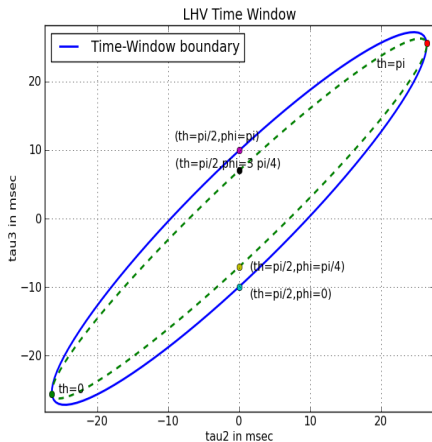


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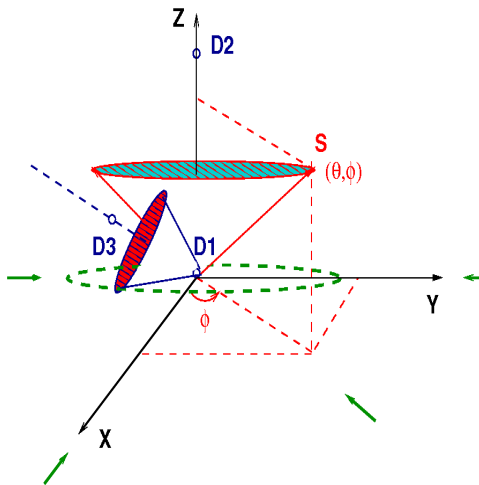


$$\tau^T \mathbf{A}_T \leq \mathbf{B} \quad \tau^T = [\tau_2 \ \tau_3], \quad \mathbf{A}_{2 \times 2}$$

Time window == Ellipse in (τ_2, τ_3)

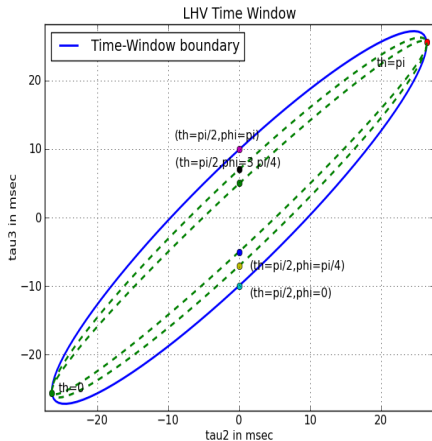


Three Detector Network: (τ_2, τ_3)

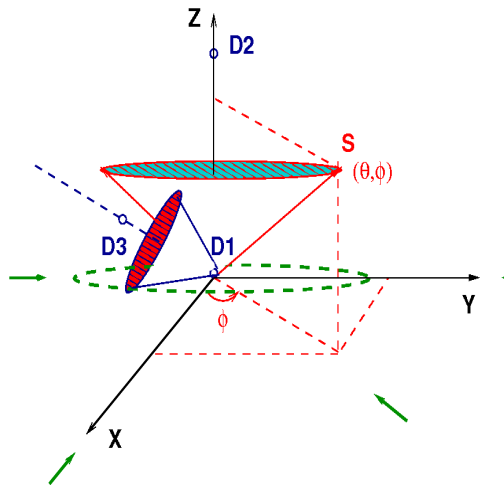


$$\tau^T \mathbf{A}_T \leq \mathbf{B} \quad \tau^T = [\tau_2 \ \tau_3], \quad \mathbf{A}_{2 \times 2}$$

Time window == Ellipse in (τ_2, τ_3)



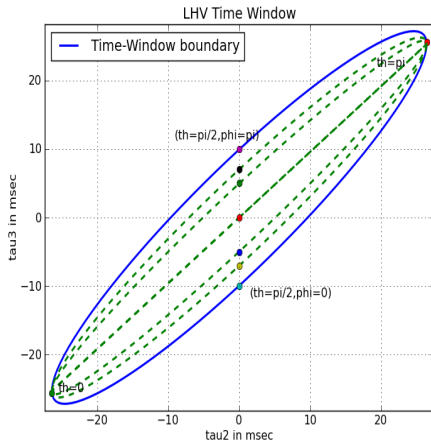
Three Detector Network: (τ_2, τ_3)



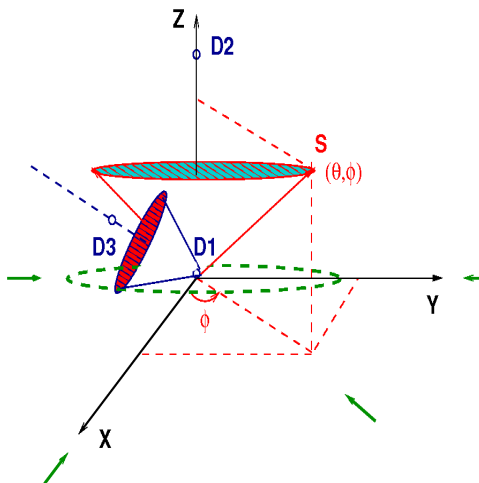
$$\tau^T \mathbf{A}_T \leq \mathbf{B}$$

$$\tau^T = [\tau_2 \ \tau_3], \quad \mathbf{A}_{2 \times 2}$$

Time window == Ellipse in (τ_2, τ_3)



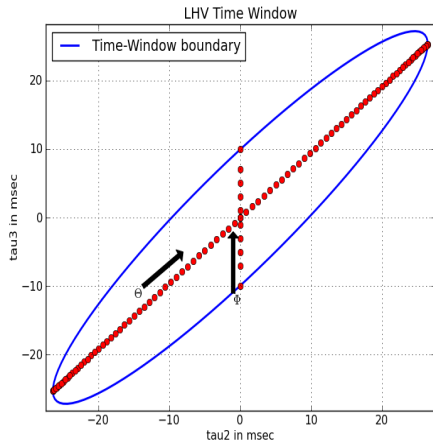
Three Detector Network: (τ_2, τ_3)



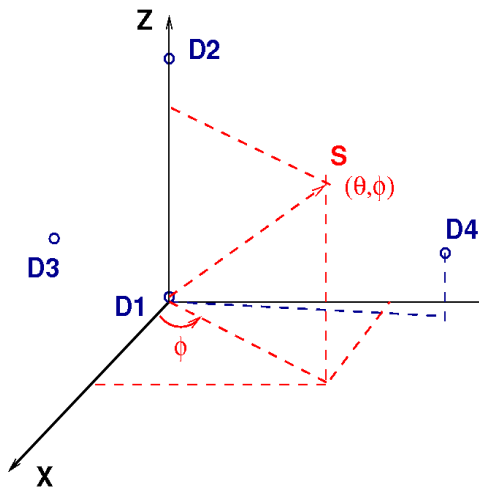
$(\theta, \pm\phi) \Rightarrow (\theta, \phi)$ – Degeneracy in ϕ
 Source above and below D1-D2-D3
 plane maps to same (τ_2, τ_3) point

$$\tau^T \mathbf{A}_T \leq \mathbf{B} \quad \tau^T = [\tau_2 \ \tau_3], \mathbf{A}_{2 \times 2}$$

Time window == Ellipse in (τ_2, τ_3)

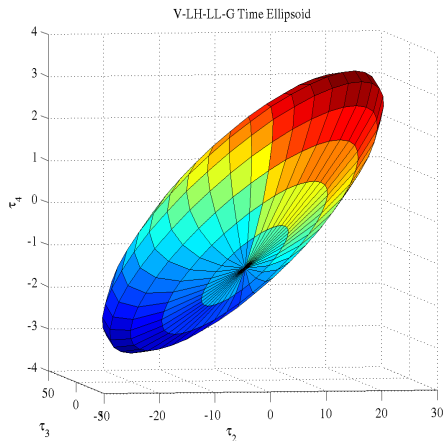


Four Detector Network: (τ_2, τ_3, τ_4)



$$\tau^T \mathbf{A}_T = \mathbf{B} \quad \tau^T = [\tau_2 \ \tau_3 \ \tau_4], \quad \mathbf{A}_{3 \times 3}$$

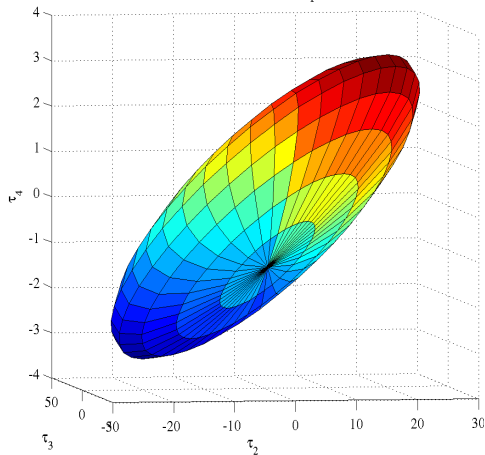
Time window: Ellipsoid in (τ_2, τ_3, τ_4)



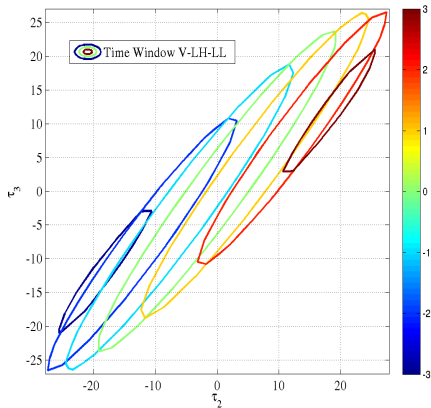
Four Detector Network: (τ_2, τ_3, τ_4)

Time window: Ellipsoid in (τ_2, τ_3, τ_4)

V-LH-LL-G Time Ellipsoid



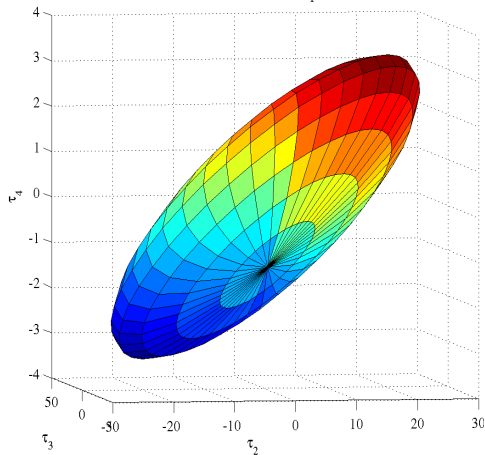
Projection on $\tau_2 - \tau_3$ plane:



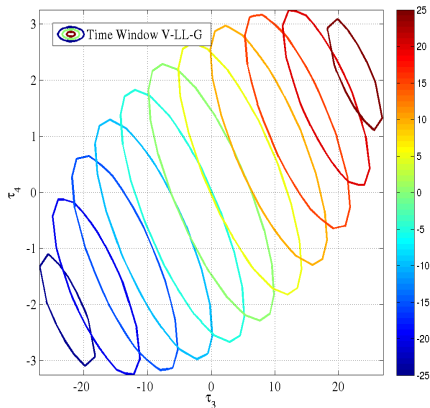
Four Detector Network: (τ_2, τ_3, τ_4)

Time window: Ellipsoid in (τ_2, τ_3, τ_4)

V-LH-LL-G Time Ellipsoid



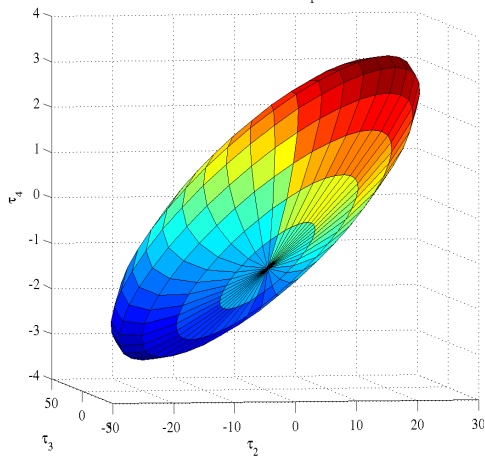
Projection on $\tau_3 - \tau_4$ plane:



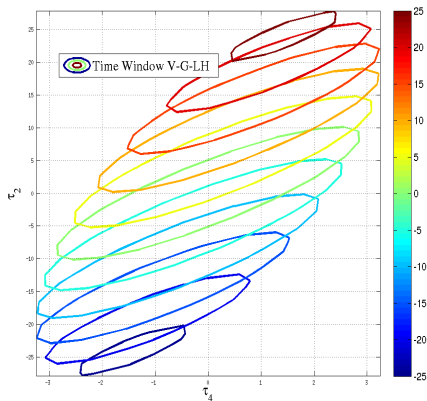
Four Detector Network: (τ_2, τ_3, τ_4)

Time window: Ellipsoid in (τ_2, τ_3, τ_4)

V-LH-LL-G Time Ellipsoid

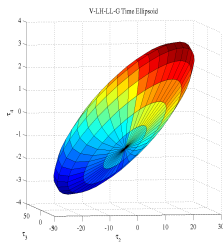


Projection on $\tau_4 - \tau_2$ plane:

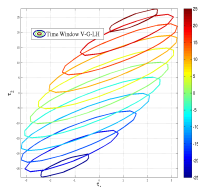


Four Detector Network: (τ_2, τ_3, τ_4)

Time window: Ellipsoid in (τ_2, τ_3, τ_4)



Projection on $\tau_4 - \tau_2$ plane:



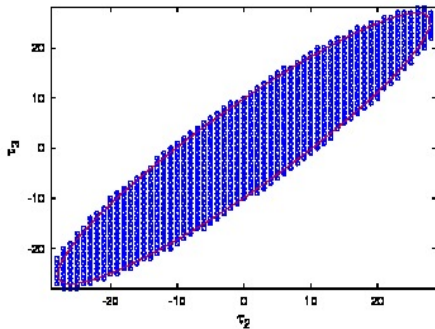
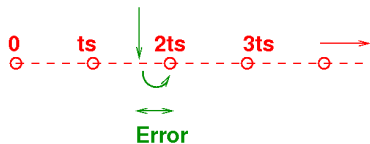
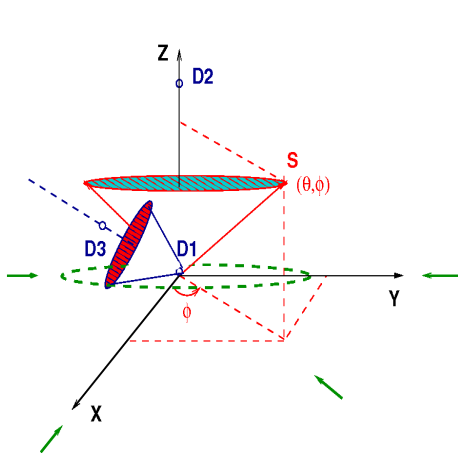
Four detectors can determine source location (θ, ϕ)

D detector network ($D \geq 4$)

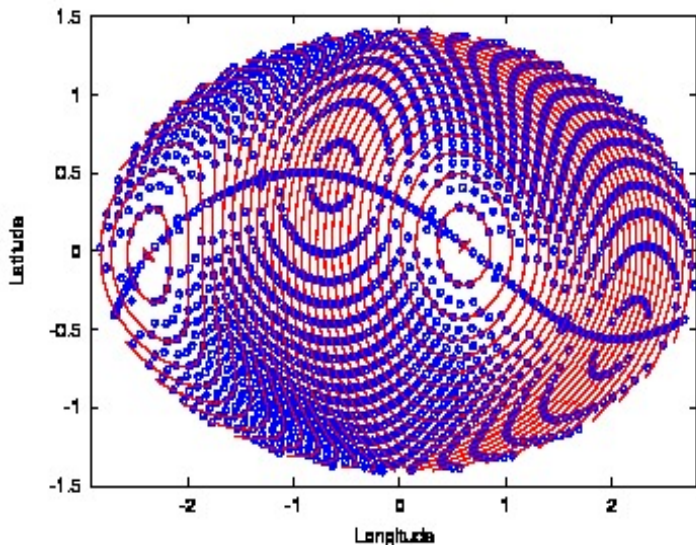
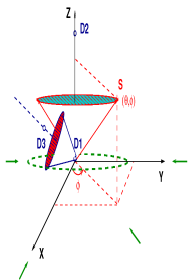
Number of ellipsoids: $D^{-1} C_3$

Each time-delay triplet gives independent estimate of (θ, ϕ) .

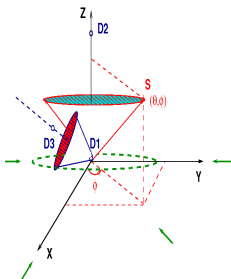
Time-delay window and the sky grid



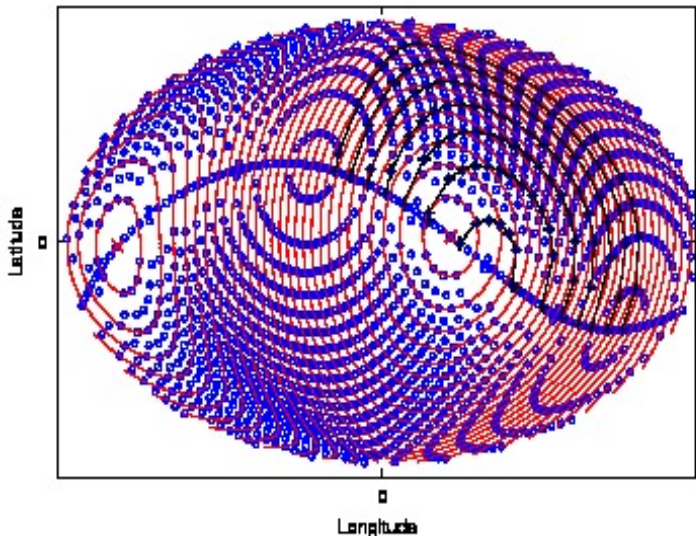
Time-delay window and the sky grid



Time-delay window and the sky grid



Red: τ_2 Contour
Black: τ_3 Contour
Blue: $\tau_2 = \tau_3 + K$

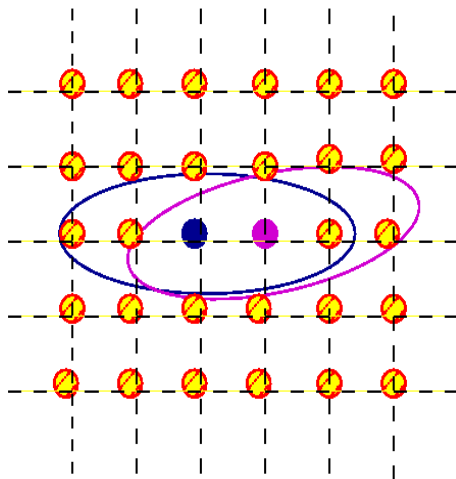


Sparse sky grid:

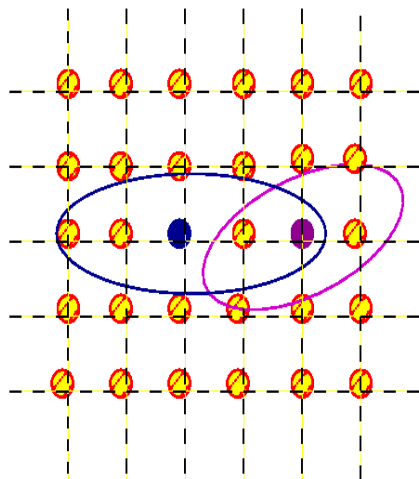
Do we need all the sky-grid points?

Tolerable SNR loss \Rightarrow Small ellipse around (θ_0, ϕ_0)
No need to sample finer than this elliptical bin

Sparse sky grid:

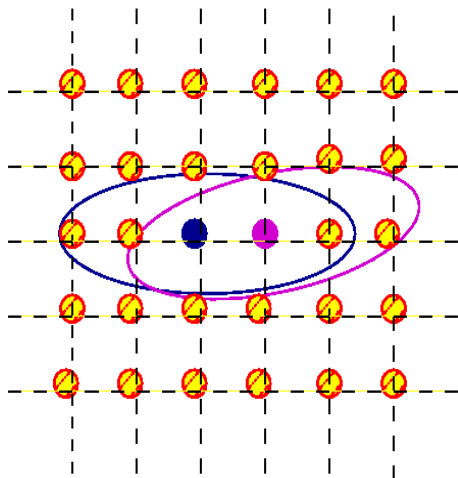


Adjacent Grid Points



Non-Adjacent Grid Points

Sparse sky grid:



Adjacent Grid Points

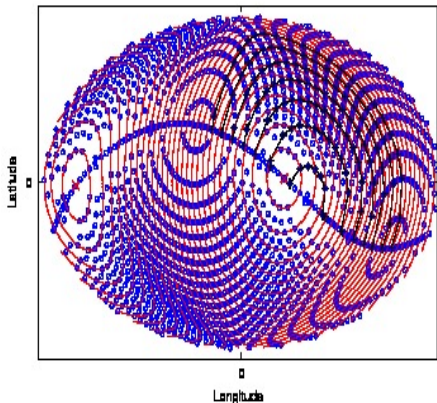
Find sparser set:

Each sample point in the original set is adjacent to at least one point in sparser set.

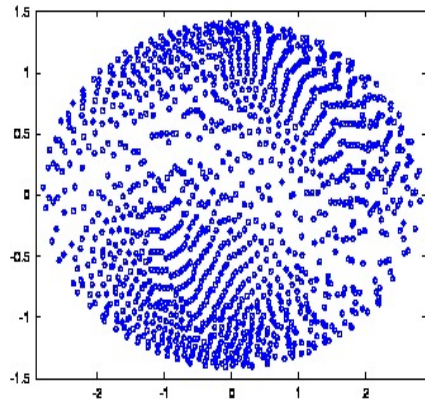
Map to the Set Covering Problem
Solve with the Greedy algorithm

Sparse sky grid:

Three detector case



Exhaustive Grid
~ 28000



Sparse Grid
~ 1200

Sky Sampling Features:

- Sparse grid uses the network geometry and the input GW signal.
- Get an exhaustive set and using the greedy algorithm, obtain a sparse set
- For sky sampling, it becomes more efficient. Due to the sphere geometry, template placement could be more taxing.
- Adjacency condition takes care of the tight spacing. There is a scope of improving the condition if required.
- Performs as good as the exhaustive set.

Extra Slides

Performance

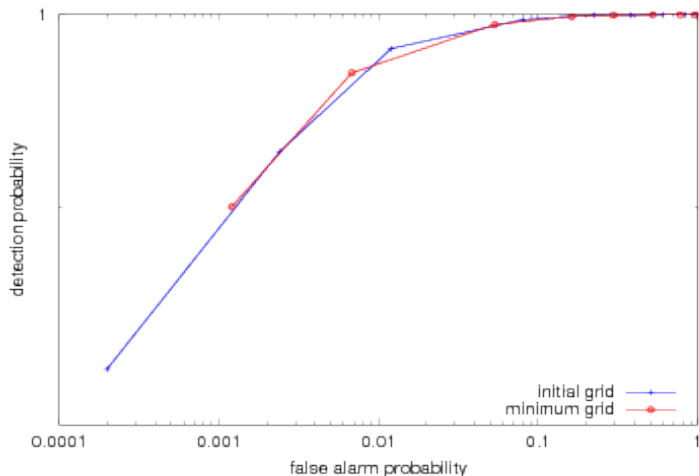
Three detector network:

Signal: Monochromatic burst

Sampling freq: 4096 Hz

$$h(t) = A(t) \exp(i\phi(t))$$

Signal freq: 150 Hz

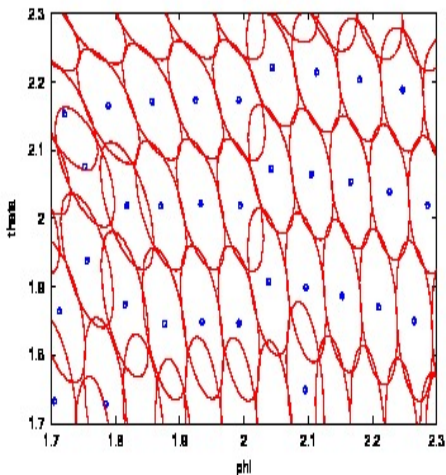


Grid is tight

Three detector network:

Signal: Monochromatic burst

Sampling freq: 4096 Hz



$$h(t) = A(t) \exp(i\phi(t))$$

Signal freq: 150 Hz

